

	L #	Hits	Search Text	DBS	Time Stamp
1	L1	87105	(head\$1 transducer\$1 slider\$1 actuator positioner vcm (voice adj coil\$1) (load adj beam\$1) HSA HGA arm\$1 (e adj block) near6 (retract\$4 ship\$4 unload\$4 park\$4 withdraw\$4 ramp)	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 13:31
2	L2	49720	(head\$1 transducer\$1 slider\$1 actuator positioner vcm (voice adj coil\$1) (load adj beam\$1) HSA HGA arm\$1 (e adj block) retract\$4 ship\$4 unload\$4 park\$4 withdraw\$4 ramp) near6 (decelerate\$4 slow\$4 ((velocit\$3 speed\$1 rate\$1) near3 (low\$5 reduc\$5 minim\$8 less\$5 below under decrease\$4 down small\$3))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 13:45
3	L3	2233	(velocit\$3 speed\$1 rate\$1) near6 (bemf bemv beme cemf cemv ceme ((back counter) adj (emf emv eme electro electromotive\$)) backemf backemv backeme counteremf countereme vemf vemv veme vbemf vbemv vbeamf vbeamv vceme vceme vcmf vcmv vcmv vcmv) near6 (((gray grey) adj code\$1) graycode\$1 greycode\$1 ((track\$1 cylinder\$1) adj (ID identif\$8 address\$2)))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 13:50
4	L4	499	(velocit\$3 speed\$1 rate\$1) near6 (((gray grey) adj code\$1) graycode\$1 greycode\$1 ((track\$1 cylinder\$1) adj (ID identif\$8 address\$2)))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:01
5	L5	185	1 and 2 and (3 4)	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:02
6	L6	1401	1 same 2	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:01
7	L7	173	6 and (360/75.cc1s. 360/78.04-78.14.cc1s.)	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:02
8	L8	107	1 and 2	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:02
9	L9	372	5 7 8	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/04/02 14:02